

Neutralized drift compression offers the possibility of very short pulses

For a parabolic pulse the longitudinal envelope equation (including longitudinal thermal spread) for bunch length l is:

$$\frac{d^2 l}{dt^2} = \frac{16\varepsilon_z^2}{l^3} + \frac{4v_0^2 g Q_a l_a}{l^2} \quad \Rightarrow \quad \left(\frac{\Delta v}{v}\right)_{\text{tilt}}^2 = 20 \left(\frac{\delta v}{v}\right)_a^2 [C^2 - 1] + 8gQ_a [C - 1]$$

Thermal
Spread + Space
Charge

where $\varepsilon_z^2 \equiv 25 \left(\langle \delta v_z^2 \rangle \langle \delta z^2 \rangle - \langle \delta v_z \delta z \rangle^2 \right)$

So if initial velocity spread $\delta v/v \sim 5 \times 10^{-4}$, initial tilt $\Delta v/v < \sim 1$, and initial perveance in drift section $Q_a = \sim 0$, final compression ratio $C = l_0/l_f \sim 10^2 - 10^3$ are possible.

For pulse durations at end of accelerator of ~ 250 ns, final pulse durations of order $\sim 0.2 - 1$ ns are possible.

How big can C be?

$$\textcircled{1}. \left(\frac{\Delta v}{v}\right)_{\text{tilt}}^2 = 20 \left(\frac{\delta v}{v}\right)_a^2 [C^2 - 1] + 8g Q_a [C - 1]$$

$$\Rightarrow C_{\text{max}} \text{ occurs if } \frac{\Delta v}{v} = \frac{\Delta v}{v}_{\text{max}} \approx 1$$

$$\rightarrow \text{If } Q_a = 0$$

$$\Rightarrow C_{\text{max}}^2 = \frac{\left(\frac{\Delta v}{v}\right)_{\text{max}}^2}{20 \left(\frac{\delta v}{v}\right)_a^2} + 1$$

$$C_{\text{max}} = \sqrt{\frac{\left(\frac{\Delta v}{v}\right)_{\text{max}}^2}{20 \left(\frac{\delta v}{v}\right)_a^2} + 1} \approx \frac{\frac{\Delta v_{\text{tilt}}}{v_a}}{4.5 \left(\frac{\delta v}{v}\right)_a}$$

$$\frac{\Delta v}{v}_{\text{max}} \leq 1$$

$$\left(\frac{\delta v}{v}\right)_a \approx \frac{\delta v_z}{v_z} \Big|_{\text{inj}} \left(\frac{E_{\text{acc}}}{E_{\text{inj}}}\right) \left(\frac{V_{\text{inj}}}{V_{\text{acc}}}\right) \left(\frac{\Delta t_{\text{inj}}}{\Delta t_{\text{acc}}}\right)$$

\downarrow \downarrow \downarrow
 ≈ 1 $\approx \frac{1}{3}$ ≈ 1

So if $\frac{\delta v_z}{v_z} \Big|_{\text{inj}} = 5 \times 10^{-4}$

$$\Rightarrow C_{\text{max}} \sim \sqrt{\frac{1}{20 \cdot (1.7 \cdot 10^{-4})^2} + 1} \sim 1315$$

② Limit on C from Kinematics:

Craig Olson noted:

$$\frac{\Delta V}{V} = \frac{2\Delta z}{z_{drift}}$$

$$\Delta z \leq l_{b,final}$$

$$z_{drift} = \frac{l_{b0}}{\Delta V/V_0}$$

$$\rightarrow \boxed{\frac{\Delta V}{V} \leq 2 \frac{\Delta V_{tilt}}{V_0} \frac{1}{C}}$$

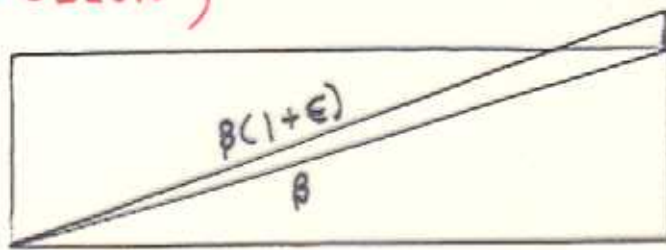
$$\Rightarrow C \leq \frac{2 \Delta V_{tilt}/V_a}{(\Delta V/V_a)} = \frac{\Delta V_{tilt}/V_a}{(\delta V/V_a)}$$

$$\text{IF } \frac{\Delta V}{V} \sim 10^3$$

$$\Rightarrow C \leq \sim 2000$$

[Limit on C from kinematics is to within a factor of order unity same limit as thermal pressure limit].

(FROM C. OLSON)



$\Delta z =$ ERROR IN FINAL POSITION. MUST BE \leftarrow

$z_d \equiv$ DRIFT DISTANCE

$t_d \equiv$ DRIFT TIME

$$z_d = \beta c t_d$$

$$z_d^* = \beta(1+\epsilon) c t_d$$

$$\Delta z = \epsilon \beta c t_d = \epsilon z_d$$

$$\epsilon_\beta = \frac{\Delta z}{z_d}$$
$$\epsilon_\epsilon = 2\epsilon_\beta$$

\Rightarrow FRACTIONAL ERROR IN ENERGY

$$\frac{\Delta V}{V} \leq \frac{\sqrt{g Q_f}}{C}$$

EXAMPLE:

IBX

$$\beta = 0.03$$
$$\Delta t = 50 \text{ ms}$$
$$\Delta z = 45 \text{ cm}$$
$$z_d = 30 \text{ m}$$

$$\epsilon_\beta = \frac{45}{3000} = 1.5\%$$

$$\epsilon_\epsilon = 3\%$$

$$Q_f \sim 10^{-3}$$
$$C \sim 10$$

DRIVER

$$\beta = 0.2$$
$$\Delta t = 10 \text{ ms}$$
$$\Delta z = 60 \text{ cm}$$
$$z_d = 400 \text{ m}$$

$$\epsilon_\beta = \frac{60}{40000} = 0.15\%$$

$$\epsilon_\epsilon = \underline{\underline{0.3\%}}$$

$$Q_f \sim 10^{-4}$$
$$C \sim 20$$